

# Microstepping steppermotordriver

## MSD-80-7.8



- 24-80V DC power supply
- H bridge bi-polar constant current microstepmotor driver
- 2-64 Microstep resolution with 16 different micro steps
- Over-current, over-voltage, over-temperature and short-circuit protected

### 1. Introduction

MSD-80-7.8 is a constant current microstep steppermotordriver, with a voltage range between 24 up to 80 Vdc. With the build-in the constant current chopping circuit, the motor runs with low vibration and noise. Wenn enabled, the drivers autocurrent reduction reduces the current to 50% of the nominal current 100 mS after receiving the last step puls, reducing the heat dissipation in both the steppermotor and steppermotor driver.

### 2. Electrical Specifications

Description	Min.	Typical	Max.	Unit
Output Current	1.8	-	7.8	A
Supply voltage	+24	-	+80	Vdc
Logic signal current	-	10	-	mA
Pulse input frequency	0	-	200	Khz
Pulse low level time	2.4	-	-	υS

### 3. Environmental conditions

Cooling	Natural or forced	
Environment	Space	Clean ( no water, dust, oil, etc )
	Storage temperature	-10°C - +80°C
	Work temperature	65°C Max
	Humidity	< 80% RH
Vibration	5.9m/s2 Max	
Weight	0.54 kgs	

**4. Current setting ( SW1, SW2 and SW3 )**

Current	SW1	SW2	SW3
1.8A	OFF	OFF	OFF
2.5A	ON	OFF	OFF
3.5A	OFF	ON	OFF
4.3A	ON	ON	OFF
5.2A	OFF	OFF	ON
6.0A	ON	OFF	ON
7.0A	OFF	ON	ON
7.8A	ON	ON	ON

**5. Auto current reduction ( SW4 )**

Full ( SW4 = ON ) and half current ( SW4= OFF )

**6. Microstep setting ( SW5, SW6, SW7 and SW8 )**

Step/rev.(for 1.8°/motor)	SW5	SW6	SW7	SW8
200	OFF	OFF	OFF	OFF
400	ON	OFF	OFF	OFF
500	OFF	ON	OFF	OFF
800	ON	ON	OFF	OFF
1000	OFF	OFF	ON	OFF
1200	ON	OFF	ON	OFF
1600	OFF	ON	ON	OFF
2000	ON	ON	ON	OFF
2500	OFF	OFF	OFF	ON
3200	ON	OFF	OFF	ON
4000	OFF	ON	OFF	ON
5000	ON	ON	OFF	ON
6400	OFF	OFF	ON	ON
8000	ON	OFF	ON	ON
10000	OFF	ON	ON	ON
12800	ON	ON	ON	ON

## 7. Pin Assignment and Description

### Input signals ( connector P1 )

Signal	Function	Description
STEP+	Step pulse input +	Usually connected to +5 Vdc.
STEP-	Step pulse input –	Makes steppermotor take one step. Rising edge triggered.
DIR+	Direction input +	Usually connected to +5Vdc.
DIR-	Direction input -	Makes the steppermotor turn left or right with every steppulse input.
ENA+	input Opto-isolated positive	Usually connected to +5Vdc
ENA-	Motor release signal	Wenn enabled ( low ) the driver cuts off the steppermotor current, thus releasing the steppermotor.

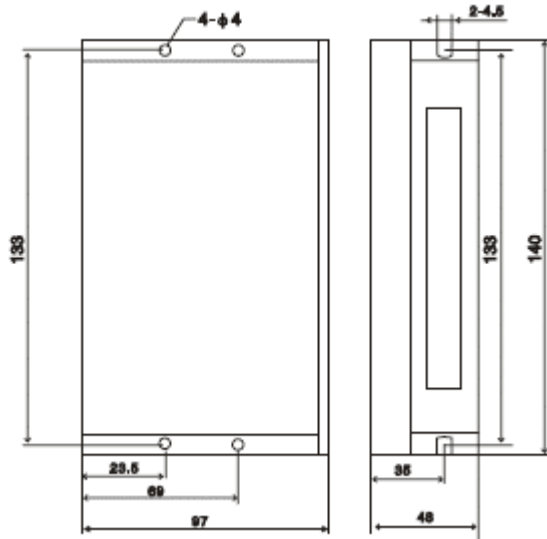
### Output signals ( connector P2 )

Signal	Function	Description
A+ A- B+ B-	Steppermotor Connections	

### Power input ( connector P2 )

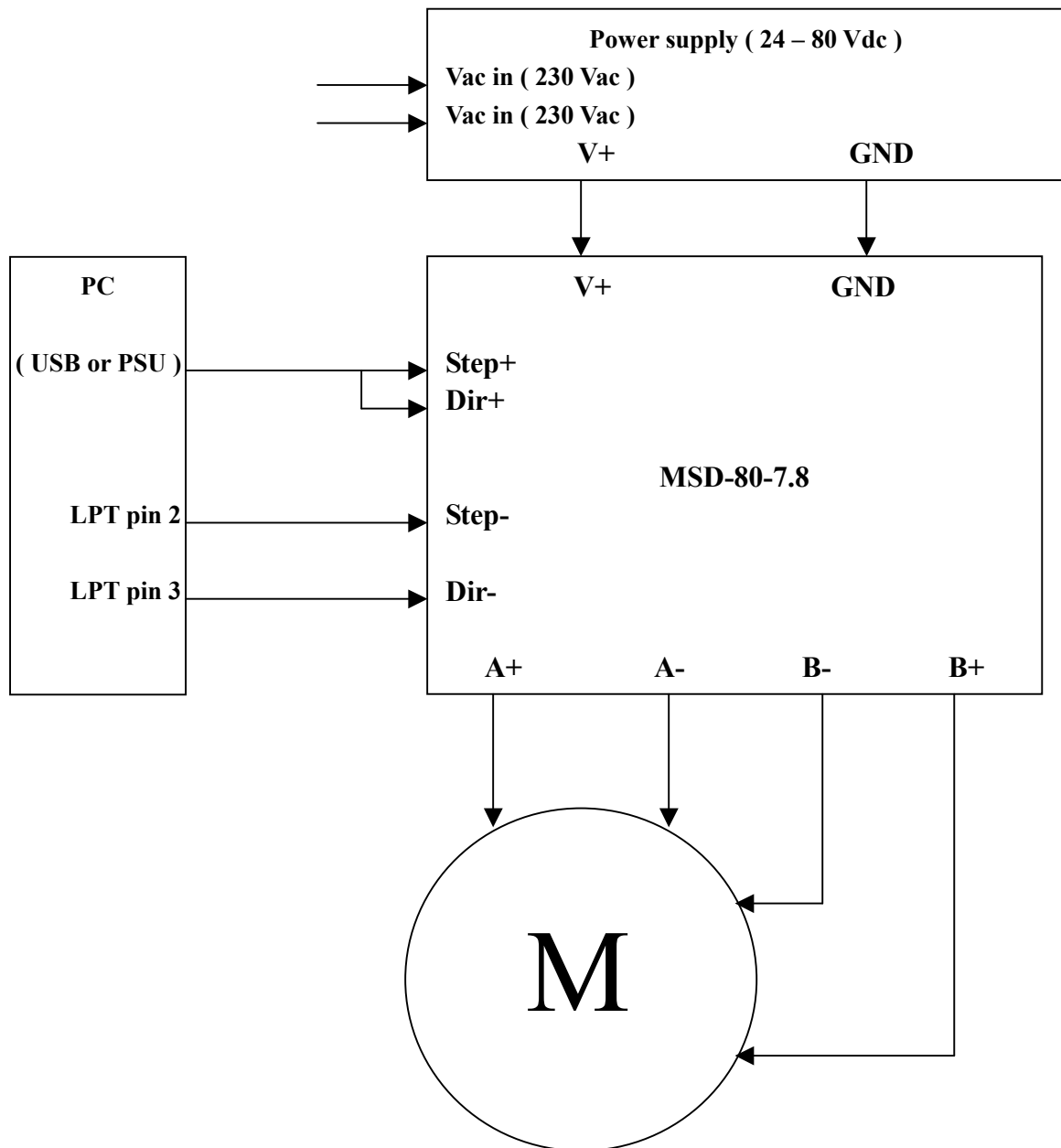
Signal	Function	Description
V+	Power	Powersupply 24 Vdc up to 80 Vdc
GND-	Ground	Powersupply ground

### 8. Mechanical Size ( mm)



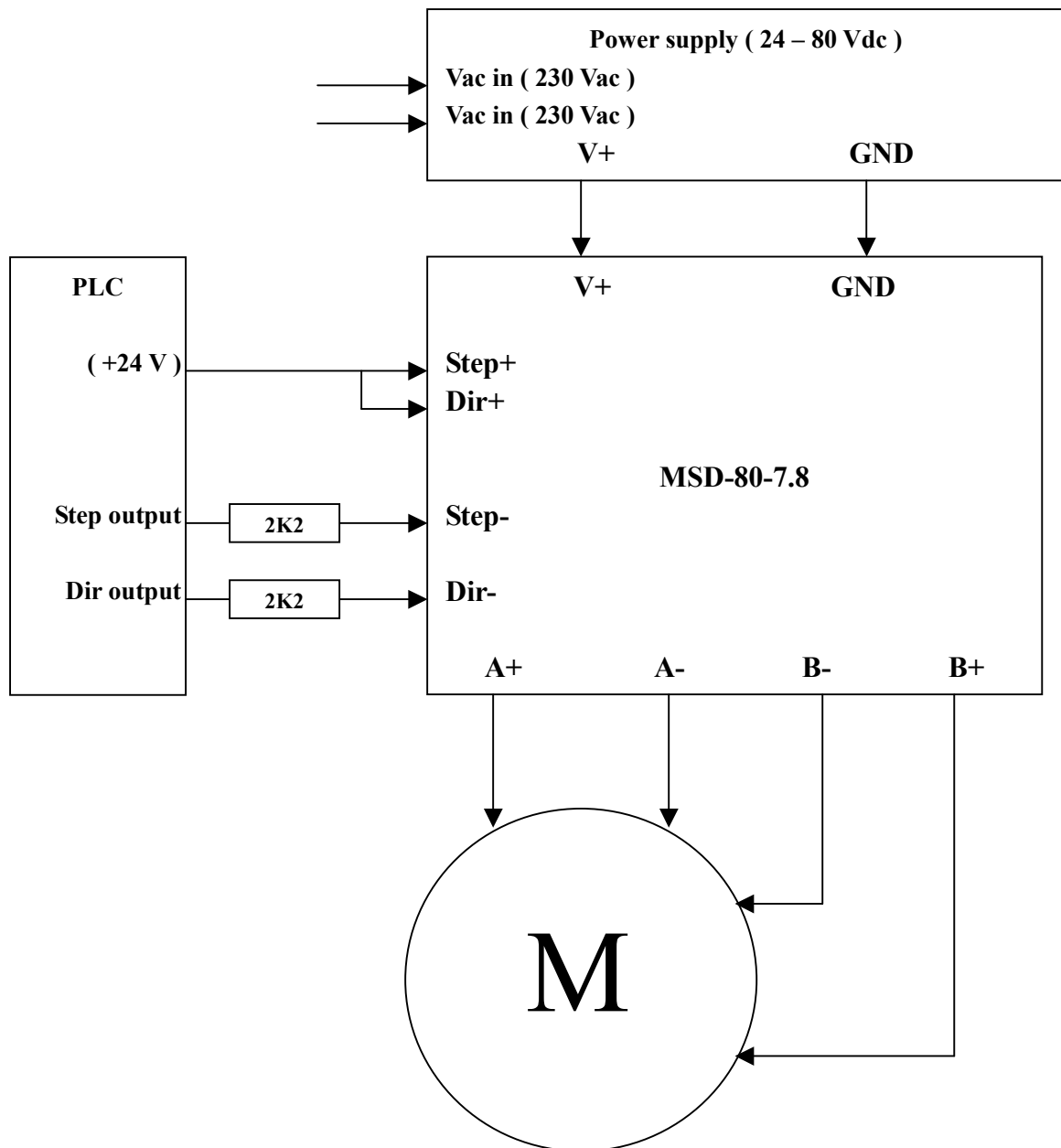
## 9. Examples of typical cnc connections

### a) Connection to a PC for most common used cnc application





**b) Connection to a 24 Vdc PLC as an industrial cnc application**



For a 12 Vdc PLC, the resistors need to be 1K types.